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Non-linguistic Evacuation-route Navigation System in Tsunami Disaster Areas

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ABSTRACT

Japan is a country prone to natural disasters such as earthquakes and typhoons. Japan has also seen a recent increase in the number of inbound foreign tourists, so it is increasingly important to communicate information to foreigners in the event of a disaster. However, language barriers remain an issue in disaster-time communications. Although there are existing multilingual systems for disaster-time communications, it is difficult to accommodate a large number of languages. Therefore, we developed a system that communicates evacuation routes and provides evacuation guidance without the use of language. The system is characterized by its ability to communicate evacuation routes through the use of only non-linguistic information, including geographic information, pictograms, and Arabic numerals. In this study, we conducted demonstration tests in tsunami disaster areas and demonstrated that the system can provide prompt evacuation guidance.

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Keywords: Evacuation-route Navigation System, Non-linguistic Interface, Tsunami Disaster Area, Response Performance

INTRODUCTION

Japan is a country prone to natural disasters such as earthquakes and typhoons. Japan has also seen a recent increase in the number of inbound foreign tourists, so it is increasingly important to communicate information to foreigners in the event of a disaster. (Aibiki et al., 2016; Hada, 2020).

However, language barriers remain an issue in disaster-time communications. Although there are existing multilingual systems for disaster-time communications, it is difficult to accommodate a large number of languages. Multilingualization cannot be comprehensive and is therefore inherently insufficient, so the use of pictorial information such as pictograms has been suggested. (Sato et al., 2020). In a survey of foreigners living in Japan and tourists from abroad, significantly more respondents answered that visual methods of communication such as gestures and pictures are more effective in communicating information during a disaster compared with language. (Hasegawa & Mukai, 2022).

Therefore, we developed a navigation system that communicates evacuation routes and provides evacuation guidance without the use of language. (Abe & Yamamoto, 2022). The system is characterized by its ability to communicate evacuation routes through the use of only non-linguistic information, including geographic information, pictograms, and Arabic numerals. The base system was developed to provide information for foreign tourists. (Abe et al., 2019; Abe et al., 2021). In this study, we evaluated the evacuation-route navigation system in tsunami disaster areas that affected by the Great East Japan Earthquake. As a result, we found that the system could quickly guide evacuees to shelters.

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NON-LINGUISTIC EVACUATION-ROUTE NAVIGATION SYSTEM

This section describes the developed non-linguistic evacuation-route navigation system. The user interface for this system consists only of non-linguistic information such as pictograms, Arabic numerals, and images. Figure 1 shows the developed system, in which pictograms and images indicate evacuation sites and landmarks. Arabic numerals indicate travel times and distances. These are superimposed over geographic information to indicate evacuation routes. The search Interface for evacuation sites is similarly non-linguistic. As Figure 2 shows, the search interface comprises buttons for selecting the means of transportation as a pictogram, and travel times can be selected as Arabic numerals from a drop-down menu. Figure 3 shows the prototype non-linguistic navigation system for evacuation routes. This prototype is implemented for the Android operating system.

However, we cannot recommend using the search interface in situations where the user's safety is not ensured, such as immediately after a disaster. In such situations, it is important that the user move quickly to a nearby evacuation site. The system thus also has functions for leading users to evacuation sites near their current location immediately after a disaster.

An algorithm based on a slime mold algorithm developed by the authors can be applied as the search method for evacuation routes. The authors have furthermore developed a method for conducting more precise searches by adding the disaster risk level as a new indicator. (Yoshitsugu et al., 2019; Yoshitsugu et al., 2020).



Figure 1: Non-linguistic Evacuation-route Navigation System (Maps © 2021 Google LLC)



Figure 2: Non-linguistic Information Retrieval Interface



Figure 3: Prototypes (Maps©2021 Google LLC)

EVALUATION OF RESPONSE PERFORMANCE

The navigation system overlays non-linguistic information such as pictograms and image onto a map, updating it as necessary to provide users with routes to nearby evacuation sites. Information acquisition time thus relies on response performance. In addition, non-linguistic information generally involves larger data sizes compared with linguistic information. Accordingly, non-linguistic evacuation-route navigation systems can thus be expected to have poorer response performance compared with linguistic systems.

Therefore, in this study, we evaluated the response performance of the developed navigation system, using the prototype shown in Figure 3. We conducted those experiments along railroad lines in tsunami disaster areas that affected by the Great East Japan Earthquake. At each station, we measured the acquisition times for three- dimensional location (latitude, longitude, and elevation) of nearby evacuation sites and three-dimensional routes (paths and slopes) from the station to the evacuation site. We took 10 measurements at each location and used the slowest time as the measured value. These experimental conditions are the same as those we used in previous demonstrations. (Abe & Yamamoto, 2021).

Table 1 shows the results of experiments at stations on the JR Senseki-Tohoku Line, which was damaged in the Great East Japan Earthquake. We performed the experiments on 17-18 December 2020. The longest acquisition time for three-dimensional location information was 2.34 s, and the longest acquisition time of three-dimensional route information was 3.17 s.

Table 2 shows the results of experiments at stations on the JR Ishinomaki Line, which was also damaged in the Great East Japan Earthquake. We performed the experiments from 23-25 June 2021. The longest acquisition time for three-dimensional location information was 2.43 s, and the longest acquisition time of three-dimensional route information was 3.78 s.

Table 3 shows the results of experiments at stations on the JR Joban Line, which was also damaged in the Great East Japan Earthquake. We performed the experiments from 6-7 September 2021. The longest acquisition time for three-dimensional location information was 2.44 s, and the longest acquisition time of three-dimensional route information was 3.35 s.

These results are equivalent to those in demonstration experiments of navigation systems we previously conducted. We thus find that the non-linguistic evacuation-route navigation system can quickly communicate evacuation routes and can be applied to evacuation guidance. Note that we measured no suspected outliers in the experiments whose results are shown in Tables 1, 2 and 3.

CONCLUSION

In this study, we described the evaluation of a non-linguistic navigation system for evacuation-route guidance. The system is characterized by its ability to communicate evacuation routes through the use of only non-linguistic information, including geographic information, pictograms, and Arabic numerals. We conducted demonstration tests in tsunami disaster areas that affected by the Great East Japan Earthquake, and the results demonstrated that the proposed system provides rapid evacuation guidance. We will continue to perform demonstration experiments in flood disaster areas.

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Table 1: Loading Time for Location Information and Route Information on the JR Senseki-Tohoku Line

Stations	Location information (s)	Route information (s)
Sendai	1.65	1.84
Higashi-Sendai	1.50	1.90
Iwakiri	1.92	2.21
Rikuzen-Sanno	1.86	2.15
Kokufu-Tagajo	2.11	2.18
Shiogama	2.34	2.02
Takagimachi	2.19	3.17
Nobiru	2.16	2.50
Rikuzen-Ono	2.08	2.28
Yamoto	2.03	2.45
Rikuzen-Akai	2.14	2.79
Ishinomakiayumino	1.91	2.79
Hebita	1.64	2.80
Rikuzen-Yamashita	1.67	2.84
Ishinomaki	1.86	2.82

Table 2: Loading Time for Location Information and Route Information on the JR Ishinomaki Line

Stations	Location information (s)	Route information (s)
Kogota	1.77	2.62
Kami-Wakuya	1.53	2.30
Wakuya	1.57	2.17
Maeyachi	2.28	2.49
Kakeyama	1.44	2.33
Kanomata	1.64	2.54
Sobanokami	1.73	2.67
Ishinomaki	1.61	2.42
Rikuzen-Inai	1.60	2.44
Watanoha	1.73	2.68
Mangokuura	1.73	2.59
Sawada	1.89	2.91
Urashuku	2.08	3.58
Onagawa	2.43	3.78

Table 3: Loading Time for Location Information and Route Information on the JR Joban Line

Stations	Location information (s)	Route information (s)
Haranomachi	1.64	2.47
Kashima	1.40	2.57
Nittaki	2.44	2.64
Soma	1.59	2.77
Komagamine	1.64	3.21
Shinchi	1.52	2.87
Sakamoto	1.41	2.72
Yamashita	1.40	2.63
Hamayoshida	1.68	2.40
Watari	1.74	2.84
Okuma	2.07	3.35
Iwanuma	1.69	2.96
Tatekoshi	1.29	2.52
Natori	1.30	2.48
Minami-Sendai	1.64	2.10
Taishido	1.64	2.18
Nagamachi	1.73	2.65
Sendai	1.81	2.31

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